## TA12

## series



## Product Segments

## - Care Motion - Industrial Motion

TiMOTION's TA12 series linear actuator is designed primarily for high-load patient lifts and bariatric beds. These sensitive applications require a linear actuator whose design is focused on safety, reliability and effortless operation. A significant feature of the TA12 is the manual release function that allows for lowering of the patient in the event of an emergency or electrical power outage. The TA12 linear actuator has obtained the UL/EN60601-1 certification and is available with an optional IP54 or 66 rating.

## General Features

Voltage of motor
Maximum load
Maximum load
Maximum speed at full load

Minimum installation dimension
Color
IP rating
Certificate
Operational temperature range
Option

12 V DC, or 24 V DC
12,000N in push
$6,000 \mathrm{~N}$ in pull
$32.3 \mathrm{~mm} / \mathrm{s}$ (with $1,500 \mathrm{~N}$ in a push or pull condition)
Stroke +210 mm
Black or grey
Up to IP66W
RoHS, EN60601-1 and IEC60601-1 compliant $+5^{\circ} \mathrm{C} \sim+45^{\circ} \mathrm{C}$
Safety nut, Hall/Reed/POT sensor(s), manual release

| Load and Speed |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CODE | Load (N) Push | Pull | Self Locking Force <br> (N) | Typical Current (A) |  | Typical Speed (mm/s) |  |
|  |  |  |  | No Load 32V DC | With Load 24V DC | No Load 32V DC | With Load 24V DC |
| Motor Speed (3800RPM, Duty Cycle 10\%) |  |  |  |  |  |  |  |
| B | 12000 | 6000 | 12000 | 2.0 | 10.0 | 7.2 | 4.0 |
| C | 7000 | 6000 | 7000 | 2.5 | 9.0 | 14.4 | 8.1 |
| D | 4000 | 4000 | 4000 | 2.5 | 9.5 | 28.7 | 16.2 |
| E | 2500 | 2500 | 2500 | 2.5 | 8.5 | 43.1 | 24.3 |
| F | 1500 | 1500 | 1500 | 2.5 | 7.5 | 57.3 | 32.3 |
| Motor Speed (3000RPM, Duty Cycle 10\%) |  |  |  |  |  |  |  |
| G | 10000 | 6000 | 10000 | 2.0 | 10.0 | 11.0 | 5.2 |
| H | 12000 | 6000 | 12000 | 2.0 | 7.5 | 5.5 | 3.1 |
| J | 7000 | 6000 | 7000 | 2.0 | 7.5 | 11.3 | 6.0 |
| K | 4000 | 4000 | 4000 | 2.0 | 7.0 | 22.7 | 12.7 |
| L | 2500 | 2500 | 2500 | 2.0 | 6.5 | 34.0 | 19.1 |
| M | 1500 | 1500 | 1500 | 2.0 | 6.0 | 45.3 | 25.5 |

## Note

1 With a 12 V motor, the current is approximately twice the current measured in 24 V ; speed will be similar for both voltages.
2 Self locking force: Tested average value when working with TiMOTION control system in push direction.
3 Current and speed: Tested avearge value when stretching in push direction.
4 Standard stroke: min needs $\geq 20 \mathrm{~mm}$, Max refer to below table.

| Load and Speed Code | Max Stroke (mm) |
| :--- | :--- |
| B, H | 450 |
| G | 750 |
| C, J | 900 |
| D, K | 1000 |
| E, L | 1200 |
| F, M | 1500 |

5 With POT signal the Max sroke.

| Load and Speed Code | Max Stroke (mm) |
| :--- | :--- |
| G | 335 |
| B, H | 335 |
| C, J | 685 |
| D, K | 685 |
| E, L | 1030 |
| F, M | 1400 |

Speed vs．Thrust


Current vs．Thrust


## Note

1 The performance data in the curve charts shows theoretical value

Speed vs．Thrust


Current vs．Thrust


## Note

The performance data in the curve charts shows theoretical value

## Drawing

Standard Dimensions
(mm)


## Retracted length (mm)

1. Calculate $A+B+C=Y$
2. Retracted length needs to $\geq$ Stroke $+Y$

| A. Front attachment | Normal | Patient Hoist |
| :--- | :--- | :--- |
| 1,2 | +220 | - |
| 6,7, C (for load<8000N) | +210 | - |
| F | - | +267 |
|  |  |  |
| B. Stroke $(\mathbf{m m})$ | Normal | Patient Hoist |
| $20 \sim 300$ | - | - |
| $301 \sim 350$ | +10 | +10 |
| $351 \sim 400$ | +20 | +20 |

For stroke over $400 \mathrm{~mm},+10 \mathrm{~mm}$ for each incremental 50 mm stroke

| C. Special Functions for <br> Spindle Sub-Assembly | Normal | Patient Hoist |
| :--- | :--- | :--- |
| 0 | - | - |
| 1 | - | - |
| 2 | +15 | - |
| 3 | +15 | - |
| 6 | - | +15 |

## Wire Definitions

| CODE* | Pin |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  | 1 | 2 | 3 | 4 | 6 |  |
|  | (green) |  | (red) | $O$ (white) |  | (black) |

## Note

* See ordering key - functions for limit switches

TA12

| Voltage | $5=24 \mathrm{~V}$, thermal protector | $6=12 \mathrm{~V}$, thermal protector |
| :---: | :---: | :---: |
| Load and Speed | See page 2 |  |
| Stroke (mm) |  |  |



| Retracted Length |
| :--- |
| $(\mathbf{m m})$ |$\quad$ See page 6

## Front Attachment <br> (mm)

## Rear Attachment (mm)

$1=\operatorname{Iron}$ CNC, clevis U , slot 8.2 , depth 17.0 , hole 10.2, T bushing
2 = Iron CNC, clevis U , slot 8.2 , depth 17.0 , hole 12.2
$6=$ Aluminum casting, clevis $U$, slot 8.2 , depth 17.0 , hole 10.2 (for load<8000N)

7 = Aluminum casting, clevis $U$, slot 8.2, depth 17.0, hole 12.2 (for load<8000N)
$\mathrm{C}=$ Aluminum casting, clevis U , slot 8.2 , depth 17.0, hole 10.2, T bushing (for load<8000N)

1 = Iron CNC, clevis U, slot 8.2, depth 17.0, hole 10.2, T bushing
2 = Iron CNC, clevis U, slot 8.2, depth 17.0, hole 12.2
$6=$ Aluminum casting, clevis $U$, slot 8.2 , depth 15.0 , hole 10.2 (for load<8000N)


| Special Functions for Spindle Sub-Assembly |  | $0=$ Without (standard) | 2 = Standard push only |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  | 1 = Safety nut | 3 = Standard push only + safety nut |  |
| Functions for Limit Switches |  | $1=$ Two switches at full retracted/extended positions to cut current $3=$ Two switches at full retracted/extended positions to send signal |  |  |
|  |  |  |  |  |
| Output Signals | $0=$ Without | 1 = One Hall sensor | 2 = Two Hall sensors | $4=\mathrm{POT}$ |
| Connector | $1=$ DIN 6pin, $90^{\circ}$ plug | $2=$ Tinned leads | $\mathrm{F}=$ DIN 6pin, $180^{\circ}$ plug | $\mathrm{G}=$ Audio plug |
| Cable Length | 1 = Straight, 500 mm | 3 = Straight, 1000mm | $5=$ Straight, 1500mm | 7 = Curly, 200 mm |
|  | $2=$ Straight, 750 mm | 4 = Straight, 1250mm | $6=$ Straight, 2000 mm | $8=$ Curly, 400 mm |

## TA12 - Patient Hoist Ordering Key

TA12

| Voltage | $\overline{5=24 \mathrm{~V}, \text { thermal protector }}$ |  |
| :--- | :--- | :--- |
| $\overline{\text { Load and Speed }}$ | $B=12000 \mathrm{~N}$ | $G=10000 \mathrm{~N}$ |

## Stroke <br> (mm)

Retracted Length $\quad$ See page 6
$(\mathbf{m m})$

## Rear Attachment <br> (mm)

$\mathrm{C}=$ Aluminum casting, clevis U , slot 8.2, depth 17.0, hole 10.2, T bushing

Front Attachment
$F=$ Aluminum casting, clevis U , slot 8.2 , depth 19.0 , hole 10.2, T bushing (for manual release)
(mm)

## Direction of Rear Attachment (Counterclockwise) $\quad 1=0^{\circ}$

| Color | 1 = Black |  | 2 = Grey (Pantone 428C) |
| :---: | :---: | :---: | :---: |
| IP Rating | $2=1$ P54 |  | 3 \| P666 |
| Emergency Release Function |  | $5=$ Manual release |  |


| Special Functions for Spindle Sub-Assembly |  | $6=$ Mechanical push onl | ety nut |
| :---: | :---: | :---: | :---: |
| Functions for Limit Switches |  | 1 = Two switches at full | ed/extended posit |
| Output Signals | $0=$ Without |  |  |
| Connector | $1=$ DIN 6pin, $90^{\circ}$ plug | F = DIN 6pin, $180^{\circ}$ plug | $\mathrm{G}=$ Audio plug |
| Cable Length | $1=$ Straight, 500 mm |  | 3 = Straight, 100 |

## Terms of Use

The user is responsible for determining the suitability of TiMOTION products for a specific application.

