

# TA2P



# **Product Segments**

# Industrial Motion

TiMOTION's TA2P series linear actuator is the high powered version of the TA2 linear actuator. A more powerful motor makes the TA2P capable of handling load ratings up to 3500N (787 pounds) while retaining its compact size.

In addition to the high power motor, the TA2P linear actuator is available with multiple choices for feedback sensors. Industry certifications for the TA2P linear actuator include IEC60601-1 and ES60601-1.

#### **General Features**

Voltage of motor 12V DC, 24V DC, 36V DC, or 48V DC

Maximum load 3,500N in push
Maximum load 2,000N in pull
Maximum speed at full load 45.0mm/s

(with 250N in a push or pull condition)

Standard stroke 20~1000mm (for load S: stroke  $\leq$  500mm)

Minimum installation dimension Stroke+108mm

(with Hall sensor(s) or without output signals)

Color Silver

Certificate IEC60601-1 and ES60601-1

Operational temperature range +5°C~+45°C

Option Potentiometer, Optical, Hall/Reed sensor(s)

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#### **Load and Speed**

CODE	Load (N)		Self	Typical Curre	ent (A)	Typical Spee	d (mm/s)	Noise
	Push	Pull	Locking Force (N)	No Load 24V DC	With Load 24V DC	No Load 24V DC	With Load 24V DC	(db)
Motor S <sub>I</sub>	peed (5200R	PM)						
Α	250	250	250	1.2	2.3	43.0	36.0	≤ 72
В	500	500	500	1.1	2.3	25.8	23.0	≤ 72
С	1000	1000	1000	1.1	2.3	14.0	11.8	≤ 70
D	1500	1500	1500	1.0	2.2	9.0	8.0	≤ 70
E	2000	2000	2000	1.0	2.2	7.1	6.2	≤ 70
Motor S <sub>I</sub>	peed (6600R	PM)						
F	250	250	250	1.6	2.8	56.5	45.0	≤ 74
G	500	500	500	1.5	2.8	32.5	28.5	≤ 74
Н	1000	1000	1000	1.5	2.8	16.5	14.3	≤ 72
K	1500	1500	1500	1.3	2.8	11.1	10.0	≤ 72
L	2000	2000	2000	1.3	2.8	8.8	7.7	≤ 72
Motor Speed (3800RPM)								
S	3500	2000	3500	0.9	2.8	3.2	2.4	≤ 72
Motor S <sub>I</sub>	peed (2200R	PM)						
Т	2000	2000	2000	0.3	1.2	3.2	2.4	≤ 68

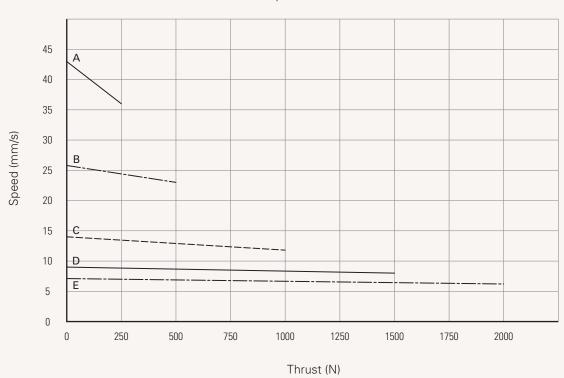
#### Note

- 1 Motor 12V current is around 2 times in 24V; Motor 36V current is around 2/3 in 24V; Motor 48V- current is around 1/2 in 24V; speed is around the same.
- ${\bf 2} \ \ {\bf Above \ self \ lock \ performance \ needs \ working \ with \ TiMOTION \ control \ system \ in \ push \ direction.}$
- 3 Please refer to approval drawing for final value.
- 4 Environmental noise ≤ 38db.

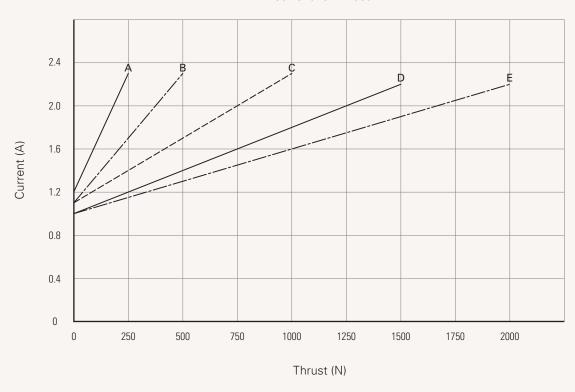


Motor Speed (5200RPM)

Speed vs. Thrust



Current vs. Thrust



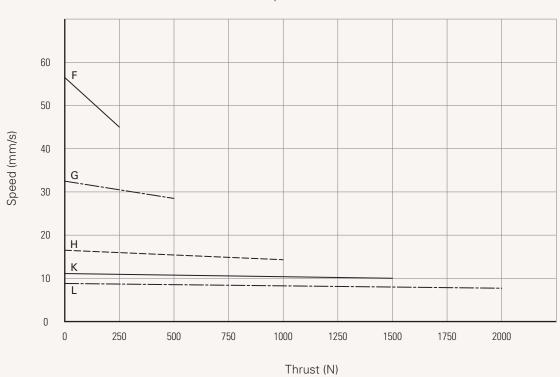
#### Note



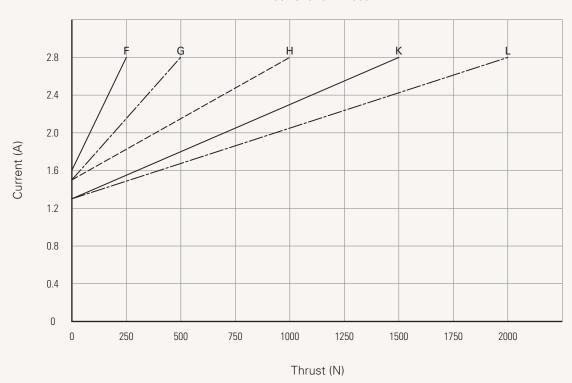
## Performance Data (24V)

Motor Speed (6600RPM)

Speed vs. Thrust



Current vs. Thrust

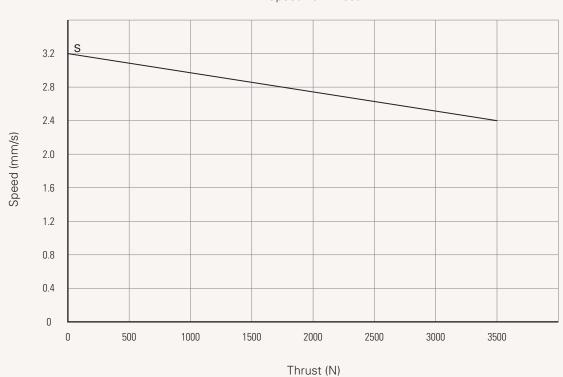


#### Note

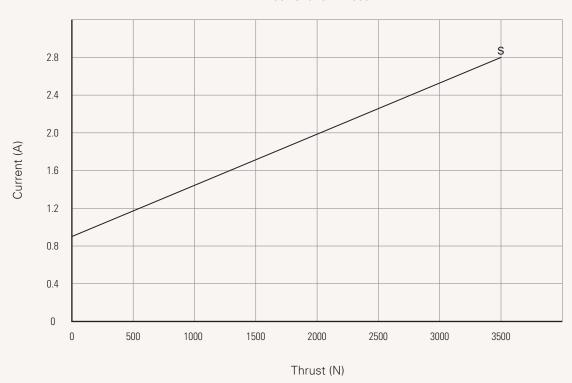


Motor Speed (3800RPM)

Speed vs. Thrust



Current vs. Thrust



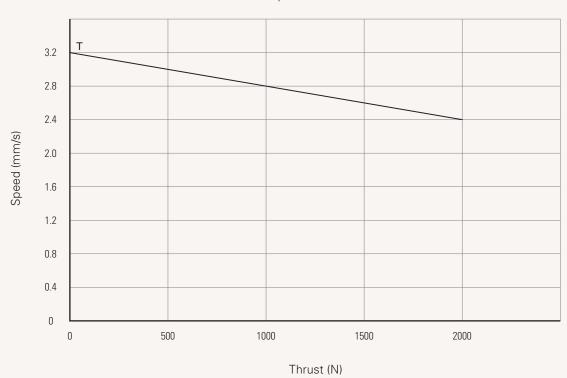
#### Note



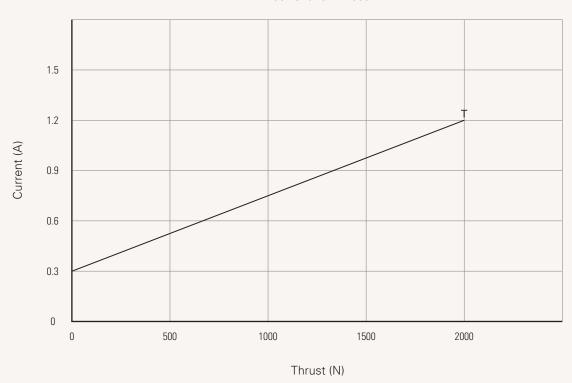
## Performance Data (24V)

Motor Speed (2200RPM)

Speed vs. Thrust



Current vs. Thrust



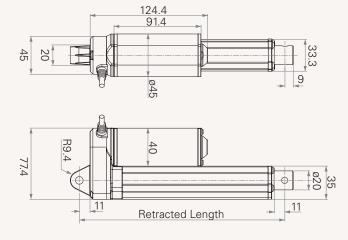
# Note



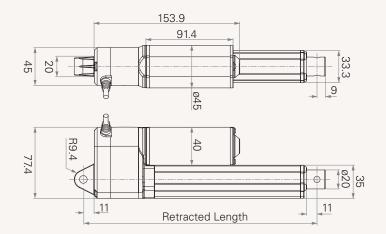
# TA2P series

## **Drawing**

Dimensions without Sensor or with Hall Sensor(s) (mm)



Dimensions with POT, Optical, or Reed Sensor (mm)





# Retracted length (mm)

- 1. Calculate A+B+C=Y
- 2. Retracted length needs to  $\geq$  Stroke+Y

A. Attachment	Rear Attachment Code			
Front Attachment Code	1, 2, 3	4, 5, 6		
1	+108	+112		
2	+108	+112		
3	+120	+124		
4	+120	+124		
5	+120	+124		

B. Stroke vs Load	Load (N)	
Stroke (mm)	< 3500	= 3500
20~150	-	+5
151~200	+2	+7
201~250	+2	+7
251~300	+2	+7
301~350	+12	+17
351~400	+22	+27

For stroke over 400mm, +10mm for each incremental 50mm stroke.

C. Output signal		
Code		
0	-	
1	+30	
2	+30	
3	+30	
4	-	
5	-	

#### **Wire Definitions**

CODE*	Pin					
	1	2	3	4	5	6
	(green)	(red)	(white)	(black)	(yellow)	(blue)
1	extend (VDC+)	N/A	N/A	N/A	retract (VDC+)	N/A
2	extend (VDC+)	N/A	middle switch pin B	middle switch pin A	retract (VDC+)	N/A
3	extend (VDC+)	common	upper limit switch	N/A	retract (VDC+)	lower limit switch
4	extend (VDC+)	common	upper limit switch	medium limit switch	retract (VDC+)	lower limit switch

#### Note



<sup>\*</sup> See ordering key - functions for limit switches

# **TA2P** Ordering Key



				Versio
Voltage	1 = 12V 2 = 24V	3 = 36V $4 = 48V$	5 = 24V, PTC	
Load and Speed	See page 2.			
Stroke (mm)				
Retracted Length mm)	See page 8.			
Rear Attachment	2 = Aluminum casting, hole 3 = Aluminum casting, hole 4 = Aluminum casting, clevi 5 = Aluminum casting, clevi	s U, slot 6.0mm, depth 10.5n	ith gear box	with gear box
Front Attachment	1 = Aluminum casting, hole 6.4mm 2 = Aluminum casting, hole 8.0mm 3 = Aluminum CNC, clevis U, slot 6.0mm, depth 16.0mm, hole 10.0mm 4 = Aluminum CNC, clevis U, slot 6.0mm, depth 16.0mm, hole 6.4mm 5 = Aluminum CNC, clevis U, slot 6.0mm, depth 16.0mm, hole 8.0mm			
Direction of rear attac	hment (counterclockwise)	1 = 90°	2 = 0°	
unctions for imit Switches	2 = Two switches at full retu 3 = Two switches at full retu	tracted/extended positions to cut current tracted/extended positions to cut current + third one in between to send signal tracted/extended positions to send signal tracted/extended positions to send signal + third one in between to send signal		
Output Signals	0 = Without 1 = POT	2 = Optical 3 = Reed sensor	4 = One Hall sensor 5 = Two Hall sensors	
Plug	1 = DIN 6pin, 90° plug	2 = Tinned leads		
Cable Length	1 = Straight, 300mm 2 = Straight, 600mm	3 = Straight, 1000mm B~H = For direct cut sys	tem, please contact TiMOTION	
IP	1 = Without	2 = IP54	3 = IP66	6 = IP66D