

JP4 series



Product Segments

Industrial Motion

TiMOTION's JP4 series inline linear actuator is most similar to the JP3, but was designed for industrial applications that require higher load and speed. Its IP69K protection ensures it will withstand high temperature, high pressure water jets, and the ingress of dust and other solid contaminants. For synchronization and position feedback, the JP4 can be equipped with Hall sensors.

General Features

Voltage of motor	12V DC or 24V DC
Maximum load	4,500N in push
Maximum load	3,000N in pull
Maximum speed at full load	24.0mm/s (with 500N in a push or pull condition)
Standard stroke	20~500mm
Minimum installation dimension	Stroke+289mm
IP rating	Up to IP69K
Color	Black or grey
Operational temperature range	-5°C~+65°C
Operational temperature range at	
full performance	+5°C~+45°C
Storage temperature range	-40°C~+70°C
An inline actuator designed for sm	nall spaces

Load and Speed

CODE	Load (N)		Self	Typical Current (A)		Typical Speed (mm/s)	
	Push	Pull	Locking Force (N)	No Load 24V DC	With Load 24V DC	No Load 24V DC	With Load 24V DC
Motor Sp	oeed (3800RP	M, Duty Cycle	e 10%)				
В	4500	3000	4500	0.75	3.5	5.1	3.2
с	3500	3000	3000	0.75	3.2	7.3	4.8
D	2500	2500	2000	0.8	3.2	10.0	6.2
Е	1500	1500	1000	0.8	2.2	13.0	10.3
F	1000	1000	700	0.8	2.2	19.0	15.5
G	500	500	500	0.8	2.0	29.0	24.0

Note

1 With a 12V motor, the current is approximately twice the current measured in 24V; speed will be similar for both voltages.

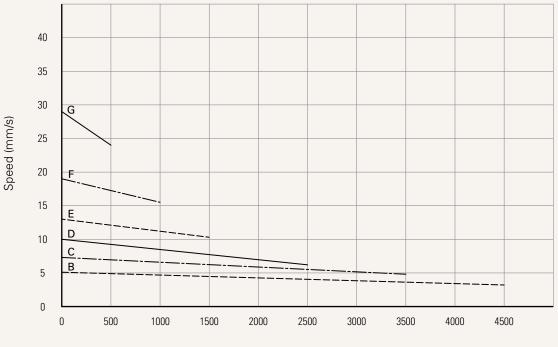
2 This self-locking force level is reached only when a short circuit is applied on the terminals of the motor. All the TiMOTION control boxes have this feature built-in.





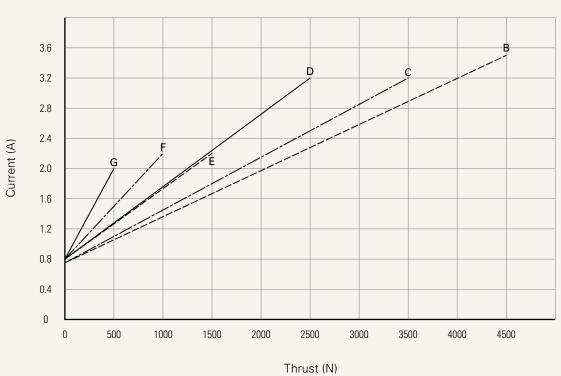
Performance Data (24V DC Motor)

Motor Speed (3800RPM, Duty Cycle 10%)



Speed vs. Thrust

Thrust (N)



Current vs. Thrust

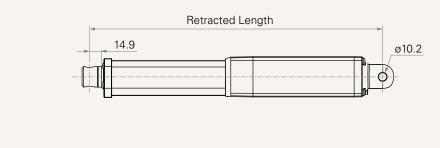
Note

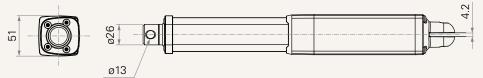
1 The performance data in the curve charts shows theoretical value.



Drawing

Standard Dimensions (mm)





Wire Definitions

CODE*	Pin					
	1	2	3	4	5	6
	🔵 (green)	🔴 (red)	(white)	(black)	😑 (yellow)	🔵 (blue)
1	extend (VDC+)	N/A	N/A	N/A	retract (VDC+)	N/A
2	extend (VDC+)	N/A	middle switch pin B	middle switch pin A	retract (VDC+)	N/A
3	extend (VDC+)	common	upper limit switch	N/A	retract (VDC+)	lower limit switch
4	extend (VDC+)	common	upper limit switch	medium limit switch	retract (VDC+)	lower limit switch

Note

* See ordering key - functions for limit switches



Retracted length (mm)

1. Calculate A+B = Y

251~300

301~350

351~400

2. Retracted length needs to \geq Stroke+Y

A. Attachment	Rear Attachment Code	
Front Attachment Code	1	
1	+289	
B. Stroke (mm)		
B. Stroke (mm) 20~150		
	-	

+20

+30

+40

For stroke over 400mm, +10mm for each incremental 50mm stroke.



JP4 Ordering Key



Voltage	1 = 12V	2 = 24V	5 = 24V, PTC	
Load and Speed	See page 2.			
Stroke (mm)				
Retracted Length (mm)	See page 5.			
Rear Attachment	1 = Aluminum casting	, U clevis, slot 4.2mm, depth 18.0m	m, hole 10.2mm	
Front Attachment	1 = #45 Steel CNC, no	slot, hole 13.0mm		
Direction of Rear Attach	ment (Counterclockwis	se) $1 = 0^{\circ}$		
Color	1 = Black		2 = Grey (Pantone 428	3C)
	1 = Without	3 = IP66	6 = IP66D	8 = IP69K
IP Rating			7 = IP68	
IP Rating	2 = IP54	5 = IP66W	7 = 11 00	
IP Rating Special Functions for Spindle Sub-Assembly	2 = IP54 0 = Without (standard		7 = 11 00	
Special Functions for	0 = Without (standard 1 = Two switches at fu 2 = Two switches at fu 3 = Two switches at fu		ut current ut current + 3rd LS to send sig end signal	
Special Functions for Spindle Sub-Assembly Functions for	0 = Without (standard 1 = Two switches at fu 2 = Two switches at fu 3 = Two switches at fu) Ill retracted/extended positions to c Ill retracted/extended positions to c Ill retracted/extended positions to s	ut current ut current + 3rd LS to send sig end signal	
Special Functions for Spindle Sub-Assembly Functions for Limit Switches	0 = Without (standard 1 = Two switches at fu 2 = Two switches at fu 3 = Two switches at fu 4 = Two switches at fu) III retracted/extended positions to c III retracted/extended positions to c III retracted/extended positions to s III retracted/extended positions to s 1 = One Hall sensor	ut current ut current + 3rd LS to send sig end signal end signal + 3rd LS to send signal	
Special Functions for Spindle Sub-Assembly Functions for Limit Switches Output Signals	0 = Without (standard 1 = Two switches at fu 2 = Two switches at fu 3 = Two switches at fu 4 = Two switches at fu 0 = Without) III retracted/extended positions to c III retracted/extended positions to c III retracted/extended positions to s III retracted/extended positions to s 1 = One Hall sensor	ut current ut current + 3rd LS to send sig end signal end signal + 3rd LS to send si 2 = Two Hall sensors	ignal

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